

Particle Settling Velocity in Sediment Transport

Executive Summary

Particle settling velocity V_s is the terminal vertical velocity reached by a sediment particle falling through a fluid under gravity. It is a fundamental parameter in sediment transport because it determines:

- Whether particles remain in suspension or deposit
- Vertical concentration profiles
- Grain-size sorting
- Residence time in the water column

Settling is governed by a dynamic force balance between particle weight, buoyancy, and fluid drag. Because the drag coefficient C_D depends on the Reynolds number Re , and Re depends on V_s , settling velocity calculations are regime-dependent and typically require iteration.

- **Stokes' Law** provides an analytical solution for very small particles in laminar flow.
- Larger particles in transitional or inertia-dominated regimes require empirical drag relationships and account for **form drag** caused by flow separation.

1. Physical Significance of Settling Velocity

Settling velocity is **not a material constant**. It emerges from the interaction between:

- **Particle properties:** size, shape, density
- **Fluid properties:** density, viscosity

In sediment transport, V_s governs:

- **Deposition vs. Suspension** – Whether particles settle out of the flow
 - **Vertical Concentration Profiles** – Distribution through the water column
 - **Selective Transport** – Grain-size sorting mechanisms
 - **Residence Time** – Time before reaching the bed
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2. Fundamental Mechanics: Force Balance

For a single particle settling in still water, three vertical forces act:

2.1 Primary Forces

Force	Formula	Description
Weight W	$W = \rho_s g V_p$	Downward gravitational force
Buoyant Force F_B	$F_B = \rho g V_p$	Upward force from displaced fluid
Drag Force F_D	$F_D = \frac{1}{2} C_D \rho A V_s^2$	Resistance opposing motion

Where:

- ρ_s = particle density
 - ρ = fluid density
 - V_p = particle volume
 - A = projected area
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2.2 Terminal Velocity Concept

When released, the particle accelerates because:

$$W - F_B > F_D$$

As velocity increases, drag increases until equilibrium:

$$F_D = W - F_B$$

At this point, acceleration ≈ 0 and terminal velocity V_s is reached.

For a spherical particle of diameter d :

$$\frac{1}{2} C_D \rho \frac{\pi d^2}{4} V_s^2 = \frac{4}{3} \pi \left(\frac{d}{2}\right)^3 (\rho_s - \rho) g$$

3. Hydrodynamic Regimes and Reynolds Number

$$Re = \frac{V_s d}{\nu}$$

Where:

- ν = kinematic viscosity

Because Re depends on unknown V_s , determining regime is essential.

3.1 Low Reynolds Number (Stokes Regime, $Re \lesssim 1$)

- Fully laminar flow
- Boundary layer attached
- No wake formation
- Drag dominated by viscous shear

Drag coefficient:

$$C_D = \frac{24}{Re}$$

Stokes' Law:

$$V_s = \frac{(\rho_s - \rho)gd^2}{18\mu}$$

Where μ = dynamic viscosity.

Key property:

$$V_s \propto d^2$$

Applicable to clay and fine silt.

3.2 Transitional Regime ($1 < Re < 10^3$)

- Flow separation begins
- Steady wake forms
- Drag transitions from viscous to pressure-dominated

C_D must be obtained from experimental curves.

3.3 High Reynolds Number ($Re \gtrsim 10^3$)

- Drag dominated by **form drag**
- Controlled by pressure differences
- $C_D \approx$ order 1
- Weak viscosity dependence

Drag crisis (smooth spheres only):

$$Re \approx 2 \times 10^5$$

Rare for natural sediment.

4. Physical Origin of Form Drag

Form drag arises from:

1. Fluid acceleration around particle sides
2. Pressure reduction along sides
3. Flow separation
4. Low-pressure wake formation

Pressure difference between front and rear surfaces produces net resisting force.

This explains the rapid increase in drag after separation.

5. Particle Shape and Natural Sediments

Natural sediment is rarely spherical.

Effects:

- Increased drag
- Slower settling
- Angular/platy particles (e.g., mica) settle more slowly

Shape corrections are introduced through:

- Modified C_D
- Shape factors (S.F.)

Common quartz sand S.F. values:

- 0.5
 - 0.7
 - 0.9
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Temperature Sensitivity

Settling velocity depends on temperature through viscosity changes, especially in the Stokes regime.

6. Iterative Calculation Procedure

Outside the Stokes regime, no closed-form solution exists.

Because:

$$V_s \leftrightarrow C_D \leftrightarrow Re$$

are interdependent.

6.1 Iteration Steps

1. Write force balance:

$$V_s = \sqrt{\frac{4gd(s-1)}{3C_D}}$$

where $s = \rho_s/\rho$

2. Assume initial C_D (e.g., 1.0)
 3. Compute V_s
 4. Compute Re
 5. Update C_D from C_D-Re curve
 6. Repeat until convergence (<1% change)
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6.2 Worked Example: 1.0 mm Quartz Sphere

Given:

- $d = 1.0$ mm
- $\rho_s = 2650$ kg/m³
- $\rho = 1000$ kg/m³
- $\nu = 1.0 \times 10^{-6}$ m²/s

Pre-computed:

$$V_s = \sqrt{\frac{0.021582}{C_D}}$$

Iteration:

- **Initial** $C_D = 1.0$
 - $V_s = 0.1469$ m/s
 - $Re = 147$
- **Iteration 1:** $C_D \approx 0.90$
 - $V_s = 0.1548$ m/s
 - $Re = 155$
- **Iteration 2:** $C_D \approx 0.88$
 - $V_s = 0.1566$ m/s
 - $Re = 157$

Converged:

$$V_s \approx 0.158 \text{ m/s} (15.8 \text{ cm/s})$$
$$Re \approx 160$$

7. Framework and Scope

Settling behavior governed by:

- Reynolds number Re
- Density contrast

$$\mathcal{R} = \frac{\rho_s}{\rho} - 1$$

7.1 Assumptions

- Single particle
 - Clear, still water
 - Steady terminal conditions
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7.2 Excluded Real-World Effects

- Hindered settling (high concentration)
 - Turbulence–particle interaction
 - Flocculation (cohesive sediment)
 - Acceleration phase
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Engineering Significance

Errors in settling velocity directly propagate into:

- Suspended load prediction
- Deposition rate estimation
- Morphodynamic modeling

Correct interpretation is essential for hydraulic and environmental engineering applications.